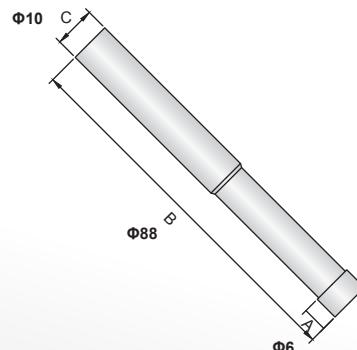


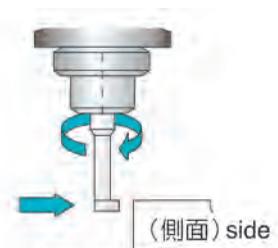
MEP

型

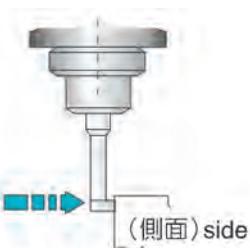
CERAMIC EDGE FINDER



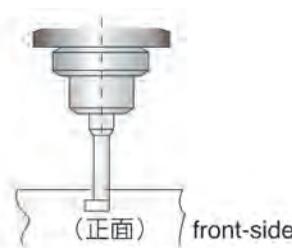
MEP-10



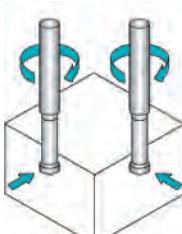
(1) 先把巡邊器回轉後，
慢慢靠近測定物。
Turn the Edge Sensor facing to
workpiece, then approach to work-
piece slowly.



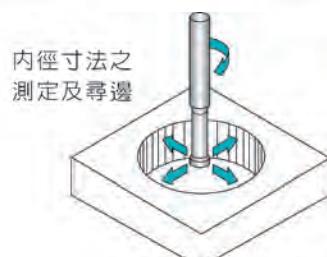
(2) 測定端子的振動到停下來時徐徐移動出去。
Once the sensor touches the work-
piece, the sensor block moves
backwards.



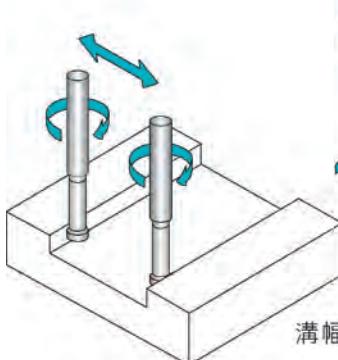
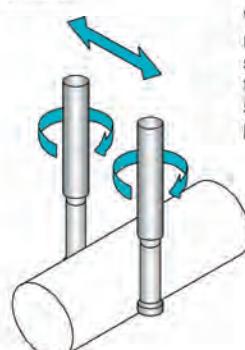
(3) 再細微的傳出時，急速的偏心的
時點，就是測定值。移送測定端
子(10m/m)的半徑5m/m時主軸與
加工物之端面就一致。
Workpiece position can be calculated by
measuring the backward distance of the
sensor block. Assuming the moving dis-
tance is 10 mm., the spindle center line is in
5 mm position. Move the senor out of work-
piece along with the workpiece edge.



基準位置之設置
set up the standard position



內徑寸法之
測定及尋邊
measure the internal
diameter



溝幅之測定

※MEP 型：具有不導磁之特性，前端使用全陶瓷之材質
※精度 : 0.005 mm

※MEP TYPE: The mep type is nonmagnetic, and the front tip wholly
made of ceramic.
※Accuracy: 0.005 mm

Ceramic[陶瓷] HV:1350°

單位/Unit:mm

ORDER NO.	TYPE	G.W. weight kgs	包裝尺寸 L x W x H
08420010	MEP-10(W)	0.06	120 x 45 x 25
08420010	MEP-10(B)	0.06	120 x 45 x 25